

CBE 30357

10/26/17

TOPICS

1) REVIEW OF FLOW PAST A SPHERE SOLUTION AND CONSEQUENCES

G.I. TAYLOR VIDEO: 17:42

- PDE SOLVED BY SEPARATION OF VARIABLES USING A SOLUTION FORM SUGGESTED BY FLOW AT BOUNDARY
- $f(\eta)$ FROM "EULER EQ"
- FLOW DISTURBANCE DECAYS SLOWLY $\sim \frac{1}{\eta}$

2) SOME ADDITIONAL IMPLICATIONS...

TERMINAL SETTLING VELOCITY

VISCOSITY OF A SUSPENSION
OF PARTICLES

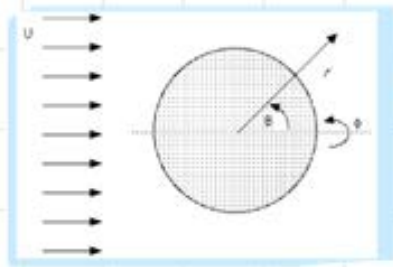
DIFFUSIVITY OF SMALL
PARTICLES AND MOLECULES

3) LIMIT IF $Re \gg 0$

VISCOSITY WOULD DROP
OUT OF EQUATIONS ...

LESS "CORRECT"
NOT AS USEFUL

4) WHAT TO DO WHEN WE
CAN'T SOLVE FLOWS IN
EXACT DETAIL



$$\left. \begin{aligned} \vec{\nabla} \cdot \vec{v} &= 0 \\ \vec{\nabla} p &= \rho \nabla^2 \vec{v} \end{aligned} \right\}$$

USE SPHERICAL COORDINATES

- CONTINUITY EQ.
- r -DIRECTION N.S. EQ.
- θ -DIRECTION N.S. EQ.

SEQUENTIALLY CONSIDER
3 PDE'S USING AN
ASSUMED FORM OF SOLUTION

$$\left. \begin{aligned} v_r &\sim f(r) \cos \theta \\ v_\theta &\sim g(r) \sin \theta \end{aligned} \right\} \begin{array}{l} \text{FROM} \\ \text{B.C.'S} \end{array}$$

THESE FORMS FOR v_r & v_θ WILL
CAUSE TRIG FUNCTIONS TO CANCEL

EULER EQ:

NOTE

$$\overset{\text{SAME}}{\overset{4}{\circlearrowleft}} f^{(4)}(r) + \overset{\text{SAME}}{\overset{3}{\circlearrowleft}} 8r f^{(3)}(r) + \overset{\text{SAME}}{\overset{2}{\circlearrowleft}} 8r^2 f^{(2)}(r) - \overset{\text{SAME}}{\overset{1}{\circlearrowleft}} 8r f'(r) = 0$$

$$\therefore f(r) \sim r^\alpha$$

SUBS AND GET
A POLYNOMIAL

$$f(r) = \frac{C_1}{3r^2} + \frac{C_2}{r} + \frac{1}{2} r^2 C_3 + C_4$$

THIS GIVES:

$$v_r = u \cos \theta \left(1 - \frac{3}{2} \frac{R}{\lambda} + 2 \frac{R^3}{\lambda^3} \right)$$

$$v_\theta = -u \sin \theta \left(1 - \frac{3}{4} \frac{R}{\lambda} + \frac{R^3}{4\lambda^3} \right)$$

FASTEST \bar{u} AS $\lambda \rightarrow \infty$

NO ACCELERATION OF FLUID
CAUSED BY DEFLECTION PAST
SPHERE

INTEGRATE:

"SKIN DRAG" SHEAR STRESS, $\tau_{\theta r}|_R$

"FORM DRAG" PRESSURE $P|_R$

AROUND SPHERE TO GET DRAG

$$\text{DRAG} = 6\pi\mu R U$$

WE GET: SETTLING VELOCITY



$\Sigma F =$ GRAVITY + BUOYANCY + DRAG



$$\Sigma F = \rho g V - \rho_f g V - 6\pi\mu R u$$

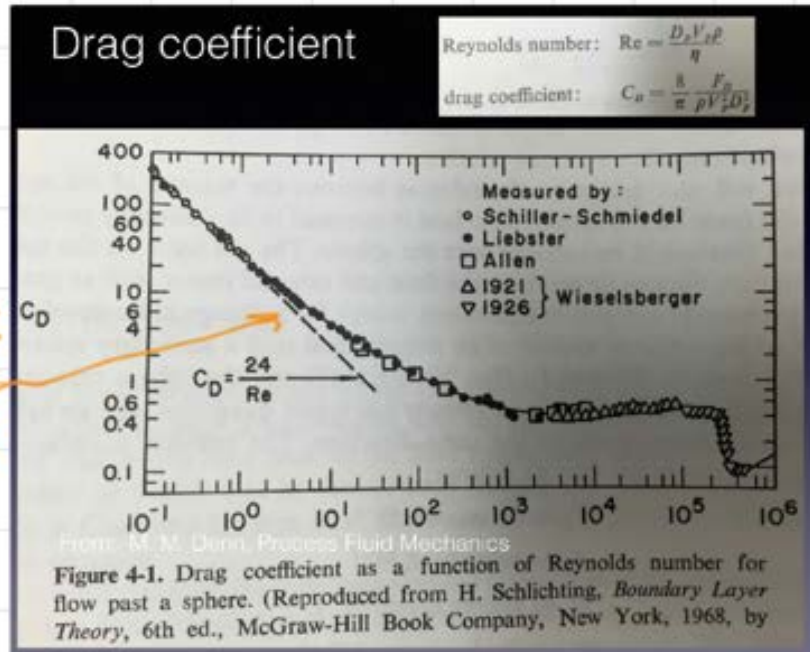
$$= \rho g \frac{4}{3} \pi R^3 - \rho_f g \frac{4}{3} \pi R^3 - 6\pi\mu R u$$

$$6\pi\mu R u = \frac{4}{3} (\rho - \rho_f) g \pi R^3$$

$$u = \frac{2}{9} \frac{(\rho - \rho_f) g R^2}{\mu}$$

MATCHES EXPERIMENTS UP TO $Re \sim .8$.

MATCHES
STOKES



... A FEW MINUTES WITH G.I. TAYLOR...

VISCOSITY OF A DILUTE ($\phi < .1$) SUSPENSION OF SPHERES

$$\frac{\overset{\text{SUSPENSION}}{M_s}}{\underset{\text{FLUID}}{M_f}} = 1 + \phi \left(\frac{M_f + \frac{5}{2} M_p}{M_f + M_p} \right)$$

ϕ → VOLUME FRACTION OF PARTICLES
 $M_p \rightarrow \infty$ FOR SOLID
 M_p → VISCOSITY OF PARTICLES

$$\frac{M_s}{M_f} = 1 + \frac{5}{2} \phi \quad \left(\text{ALSO DUE TO EINSTEIN} \right)$$

EITHER DROPS OR BUBBLES
WILL SIGNIFICANTLY INCREASE
VISCOSITY

DRAG ON A BUBBLE:

$$F_D = 4\pi\eta R U$$

ALMOST AS LARGE AS A SOLID PARTICLE !!

VISCOSITY OF LIQUID IN LIQUID SUSPENSION WILL MOST LIKELY BE HIGHER THAN EITHER COMPONENT

DIFFUSIVITY

EINSTEIN USED DRAG TO CALCULATE DIFFUSIVITY OF A PARTICLE

$$D = \frac{kT}{6\pi\eta R}$$

Annotations:
- k : **BOLTZMANN CONSTANT**
- R : **PARTICLE RADIUS**
- D : **PARTICLE DIFFUSIVITY**

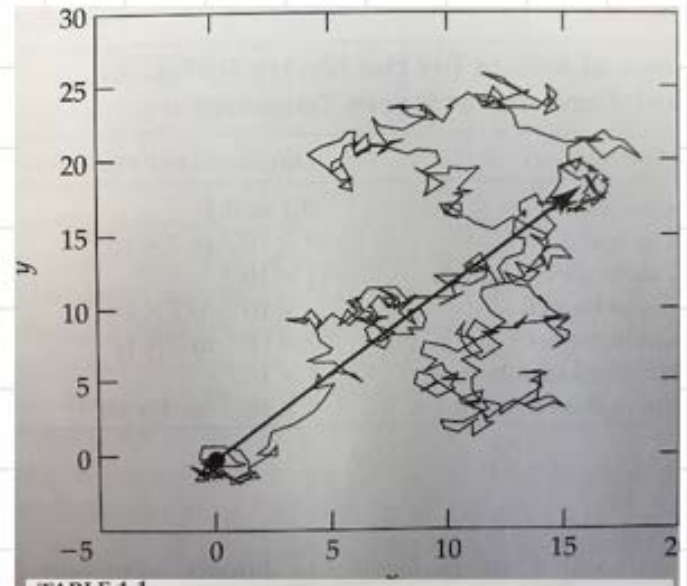


TABLE 1.1

Range of Values for the Binary Diffusion Coefficient, D_{ij} , at Room Temperature

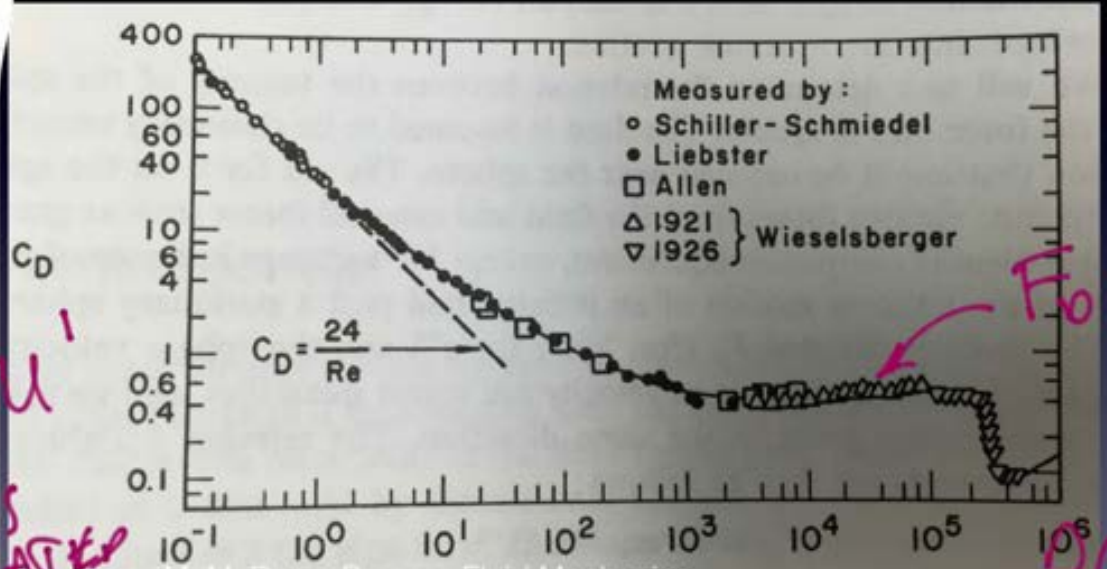
Diffusing quantity	Diffusion coefficients ($\text{cm}^2 \text{s}^{-1}$)
Gases in gases	0.1 to 0.5
Gases in liquids	1×10^{-7} to 7×10^{-5}
Small molecules in liquids	1×10^{-5}
Proteins in liquids	1×10^{-7} to 7×10^{-7}
Proteins in tissues	1×10^{-7} to 7×10^{-10}
Lipids in lipid membranes	1×10^{-9}
Proteins in lipid membranes	1×10^{-10} to 1×10^{-12}

DRAW ON SPHERE, TERMINAL VELOCITY IF $Re > 1$

Drag coefficient

Reynolds number: $Re = \frac{D_p V_p \rho}{\eta}$

drag coefficient: $C_D = \frac{8}{\pi} \frac{F_D}{\rho V_p^2 D_p^2}$



$F_D \sim u^1$
 VISCOUS DOMINATED

$F_D \sim u^2$
 INERTIA DOMINATED

From: M. M. Denn, Process Fluid Mechanics
Figure 4-1. Drag coefficient as a function of Reynolds number for flow past a sphere. (Reproduced from H. Schlichting, *Boundary Layer Theory*, 6th ed., McGraw-Hill Book Company, New York, 1968, by

WIKIPEDIA The Free Encyclopedia

Drag coefficient

From Wikipedia, the free encyclopedia

In fluid dynamics, the drag coefficient (commonly denoted as c_d , c_x or C_D) is a dimensionless quantity that is used to quantify the drag or resistance of an object in a fluid environment, such as air or water. It is used in the drag equation in which a lower drag coefficient indicates the object will have less aerodynamic or hydrodynamic drag. The drag coefficient is always associated with a particular surface area.^[1]

The drag coefficient of any object comprises the effects of the two basic contributors to fluid dynamic drag: skin friction and form drag. The drag coefficient of a lifting airfoil or hydrofoil also includes the effects of its induced drag.^{[2][3]} The drag coefficient of a complete structure such as an aircraft also includes the effects of interference drag.^{[4][5]}

Contents [hide]

- Definition
- Background
- Drag coefficient c_d examples
 - 3.1 General
- Aircraft
- Slant and streamlined body flow
 - 5.1 Concept
 - 5.1.1 Practical example
- See also
- Notes
- References

Definition [edit]

The drag coefficient c_d is defined as

$$c_d = \frac{2F_D}{\rho u^2 A}$$

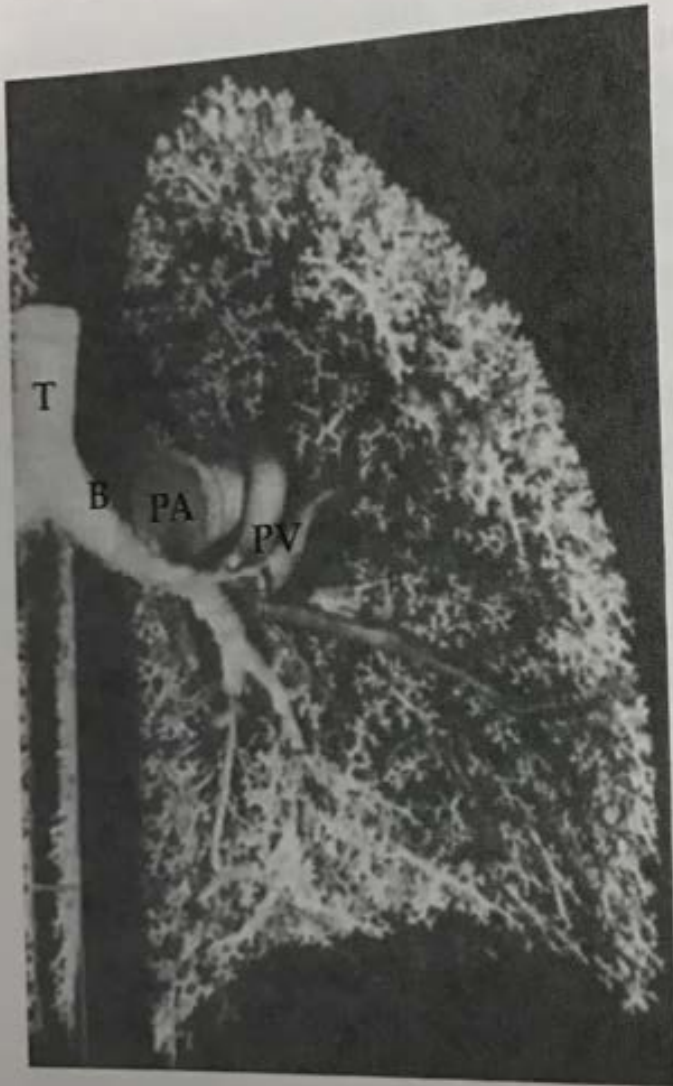
where:

- F_D is the drag force, which is by definition the force component in the direction of the flow velocity.^[6]
- ρ is the mass density of the fluid.^[7]
- u is the flow speed of the object relative to the fluid.
- A is the reference area.

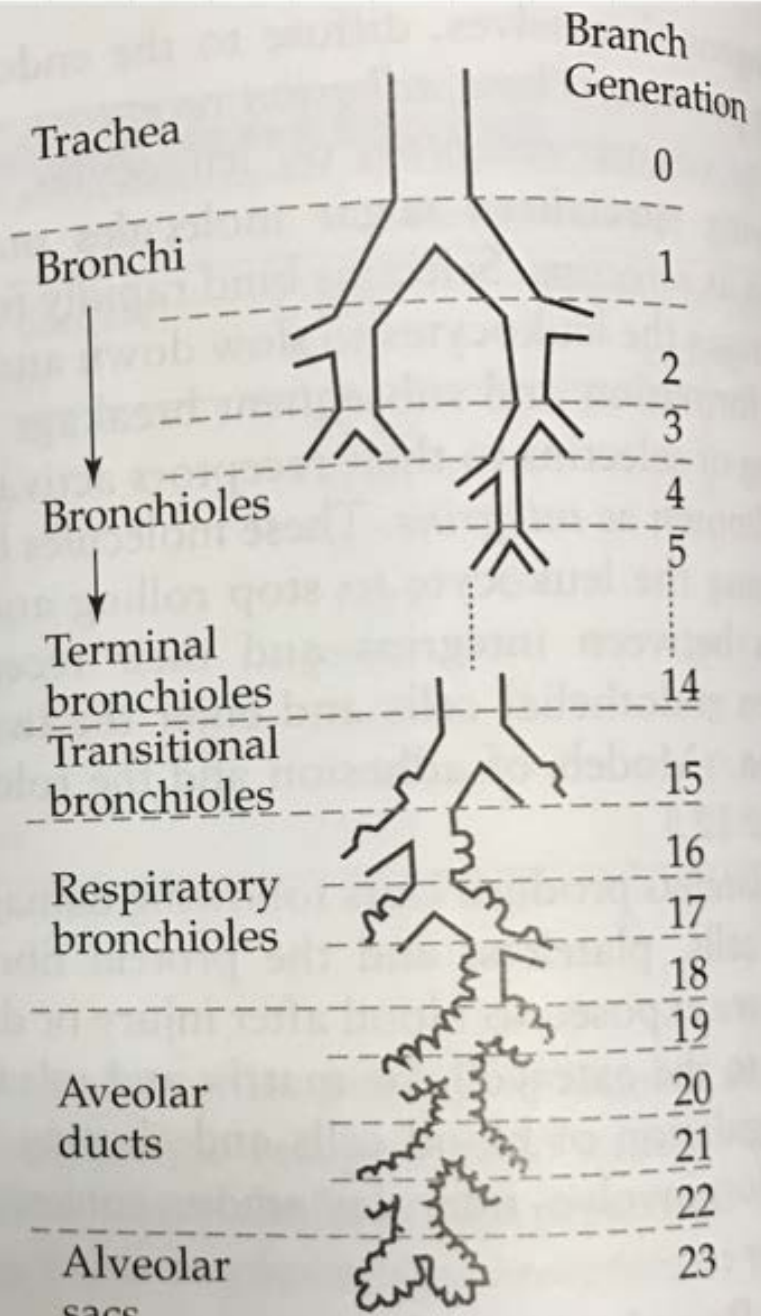
Shape	Drag Coefficient
Sphere	0.47
Half-sphere	0.42
Cube	0.80
Cone	1.05
Angled Cone	0.80
Long Cylinder	0.90
Short Cylinder	1.15
Streamlined Body	0.04
Streamlined half-body	0.08

Measured Drag Coefficients
 Drag coefficients in fluids with Reynolds number approximately 10^5

OUR LUNGS...

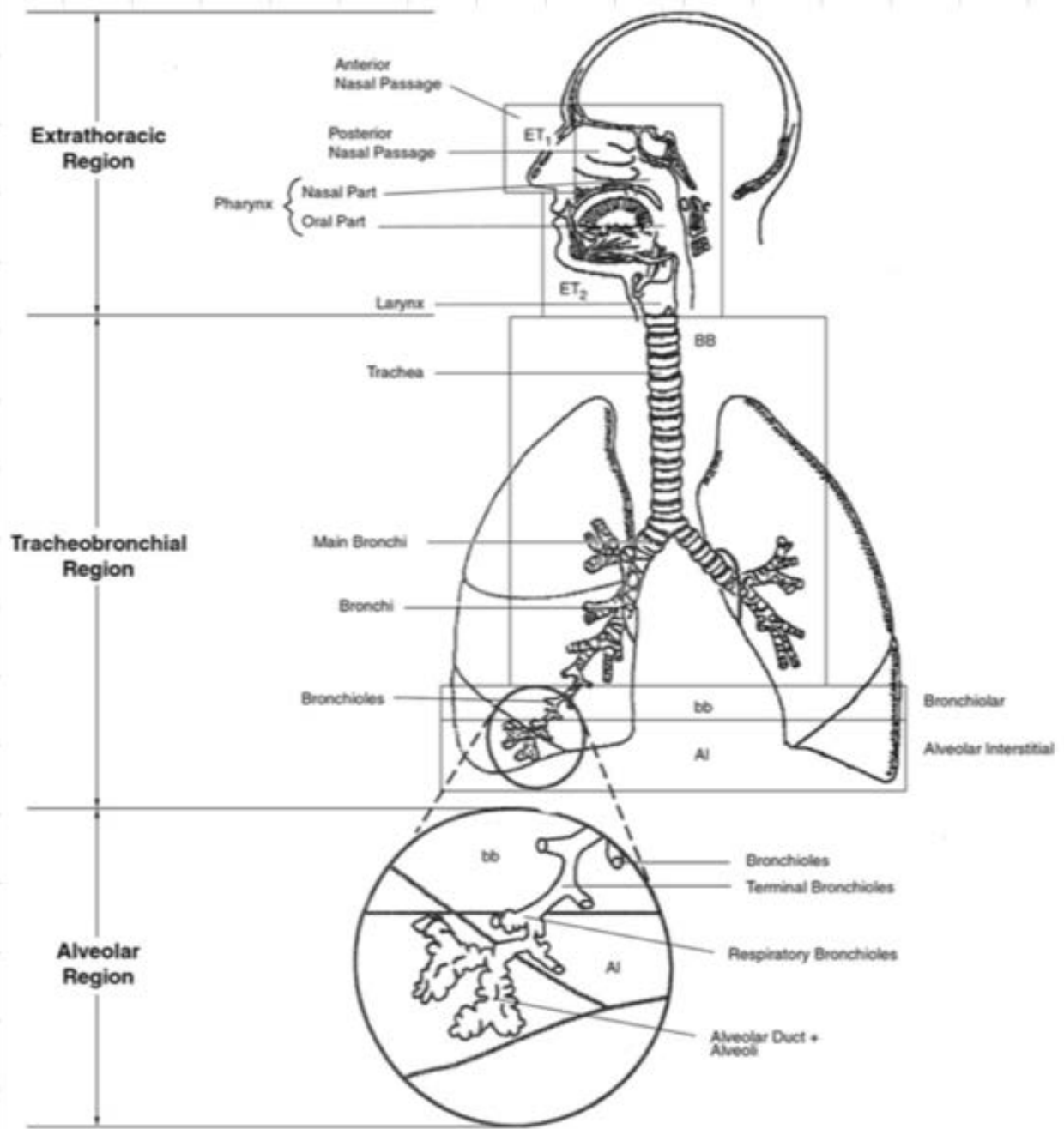


(a)



(b)

FIGURE 1.13 (a) Cast of a human lung, showing the trachea (T), one bronchus (B), the pulmonary artery (PA), and the pulmonary vein (PV). (b) Schematic of the organization of the airways in the human lung. (From Ref. [13], used with permission.)



TORTUOUS PATH, PARTICLES
 STICK TO WALL: CLEARED
 BY CILIA.
 LONG PATH: ONLY LAST ~5
 BRANCHES ABSORB
 OR, COULD BREATHE BACK OUT.

PARTICLE CLEARING MECHANISMS

2

T.C. Carvalho et al. / International Journal of Pharmaceutics 406 (2011) 1-10

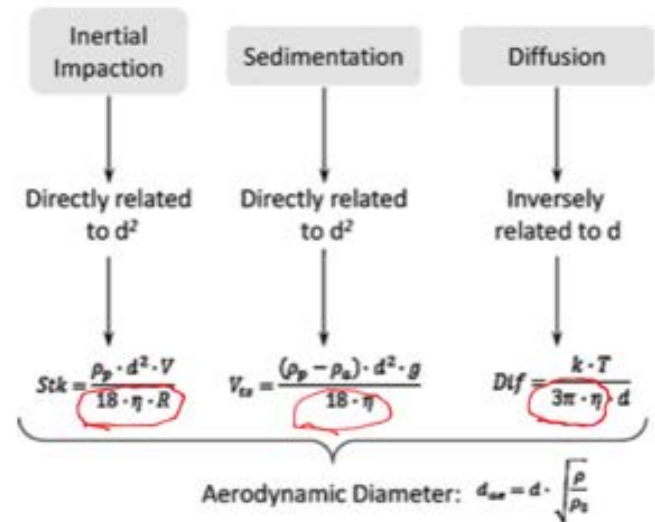
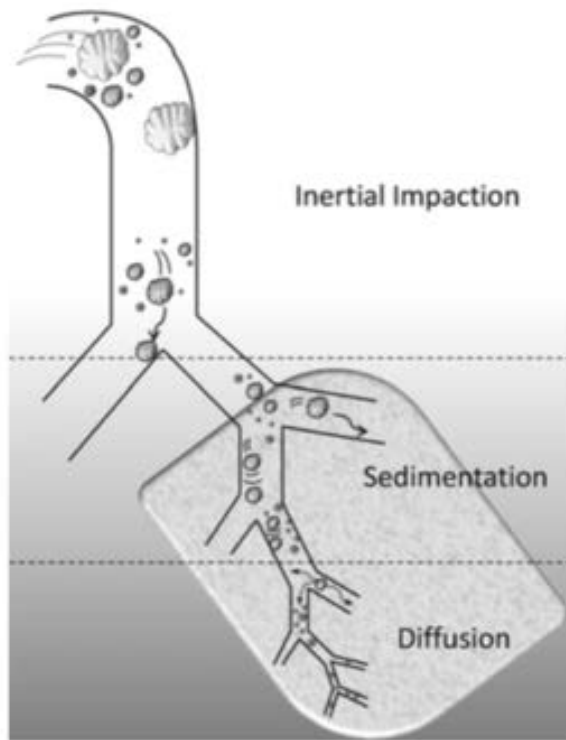


Fig. 2. The influence of particle size on deposition. d : particle diameter; Stk : Stokes number; ρ_p : particle density; V : air velocity; η : air viscosity; R : airway radius; V_{ts} : terminal settling velocity; ρ_a : air density; g : gravitational acceleration; Dif : diffusion coefficient; k : Boltzmann's constant; T : absolute temperature; d_{ae} : aerodynamic diameter; ρ_0 : unity density.

B , mass, m , and velocity, v , according to Eq. (1) (Gonda, 2004):

WHERE DO EQUATIONS COME FROM?

SOLUTION TO NAVIER-STOKES EQUATIONS FOR FLOW PAST A SPHERE: $Re \Rightarrow 0$

SEEMS LIKE IT IS SAFE TO SAY THAT YOU ARE OPTIMIZED FOR THE TRADEOFFS OF EFFICIENT BREATHING VERSUS PROTECTION FROM PARTICLES

The respiratory tract is especially designed, both anatomically and functionally, so that air can reach the most distal areas of the lungs in the cleanest possible condition. Nasal hairs, nasal turbinates, vocal chords, the cilia of the bronchial epithelium, the sneeze and cough reflexes, etc., all contribute to this filtering process. And, on most occasions it is properly done. But human beings are full of paradoxes: an efficient system, designed to avoid certain

particles from penetrating into the lungs, is at the same time used to intentionally deposit drugs in the airways and even for these to reach the alveoli in the best possible condition. It is thus necessary to get around the defense systems by evading reflex arcs, mucus layers, ciliary movements, etc., so that, with the inspiratory flow, the molecules that can improve diseases are deposited in the lungs. A system that evolved over time in order to filter and clean the air should be dodged in order to deposit other substances that we deliberately want to reach the inside of the organism. Without a

What if the Reynolds number is large, $\gg 1$?

RESCALE PRESSURE

$$p^* \equiv \frac{p}{\rho u^2}$$

$$\text{Re} \left(\frac{\partial \vec{u}^*}{\partial t^*} + \vec{v}^* \cdot \nabla^* \vec{v}^* + \nabla^* p^* \right) = \nabla^{*2} \vec{v}^* \approx 0$$

TERMED "INVISCID" OR "IDEAL"
FLOW

IF NO VISCOSITY:

▶ CAN'T IMPOSE NO SLIP

CAN CALCULATE LIFT BUT
NOT DRAG ON A WING

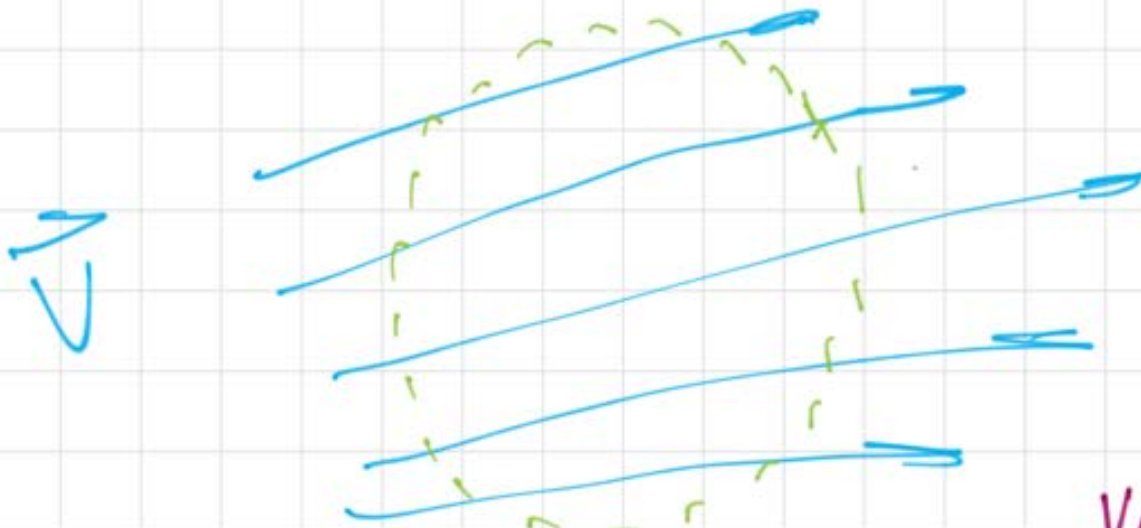
We need to be able to solve problems when:

A. Details of flow are not known

B. Large scale of flow suggests that details should not matter.

TO DO THIS WE WILL USE
INTEGRATED FORMS OF
DIFFERENTIAL BALANCES

FOR MASS CONSERVATION



FOR ALL MASS INSIDE  VOLUME INTEGRAL

CONTINUITY:

$$\int_V \frac{\partial \rho}{\partial t} dV = \int_V -\vec{\nabla} \cdot \rho \vec{v} dV$$

TOTAL
MASS IN V

$$\int_V \frac{\partial \rho}{\partial t} dV = \frac{\partial}{\partial t} \int_V \rho dV = \frac{dm}{dt}$$

$$\int_V \vec{\nabla} \cdot \rho \vec{v} dV = \int_S \rho (\vec{v} \cdot \vec{n}) dS$$

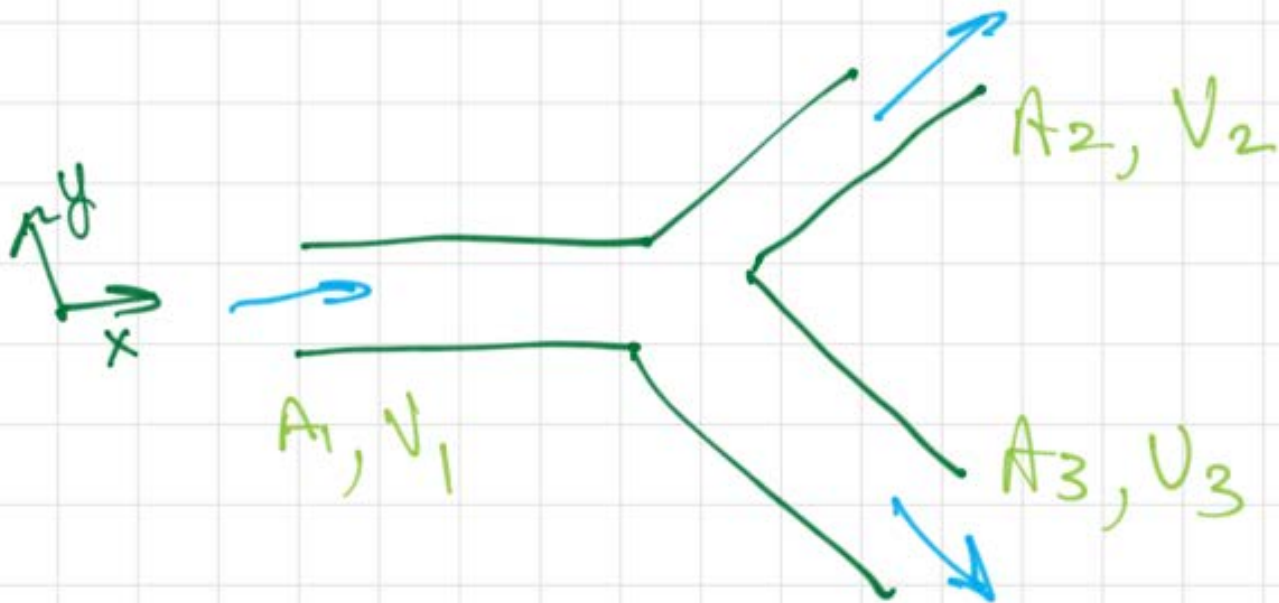
DIVERGENCE

THEOREM

THIS ALLOWS US
TO KEEP TRACK OF
MASS INSIDE BY
WATCHING INFLOWS AND
OUT FLOWS

$$\therefore \frac{dm}{dt} = - \int s(\vec{v} \cdot \vec{n}) ds$$

LOOK AT A SIMPLE CASE
FOR WHICH WE KNOW ANSWER



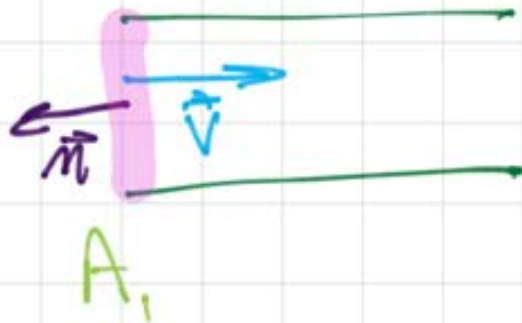
PICK S.S. $\frac{dm}{dt} = 0$

INTEGRAL IS NON-ZERO ONLY
AT OPENINGS WHERE \vec{v} IS
NON-ZERO

INFLOW \nearrow)

$$-\int_S (\vec{v} \cdot \vec{n}) ds$$

AREA 1



$$\vec{v} \cdot \vec{n} = -v_x$$

TAKE $\rho = \text{CONST}$

$$-\int_{A_1} \rho (\vec{v} \cdot \vec{n}) ds = -\rho \int_{A_1} -v_x ds$$

$$= \rho \langle v \rangle_1 A_1$$

RATE OF
MASS FLOW
IN

$$= \rho Q_1$$

DENSITY \nearrow VOLUMETRIC
FLOW
RATE

@2

$$\vec{v} \cdot \vec{n}$$

IS NOT
JUST v_x OR
 v_y , BUT IT
IS ALL OF THE 'V'

$$-\int_{A_2} \epsilon \vec{v} \cdot \vec{n} ds = -\int_{A_2} \epsilon v_z ds$$

$$= -\epsilon \langle v \rangle_z A_2$$

$$= -\epsilon Q_2$$

↑ NO
"-"
SIGN

@3

$$-\int_{A_3} \epsilon (\vec{v} \cdot \vec{n}) ds = \epsilon \langle v \rangle_z A_3$$

$$= Q_3 A_3$$

∴

$$0 = \rho \langle v \rangle_1 A_1 - \rho \langle v \rangle_2 A_2 - \rho \langle v \rangle_3 A_3$$

$$\frac{dm}{dt} = \rho \sum_{i \text{ IN}} \langle v \rangle_i A_i - \rho \sum_{j \text{ OUT}} \langle v \rangle_j A_j$$

USEFUL IN THIS FORM,

FOR TURBULENCE IN PIPES

AND DUCTS, VELOCITY PROFILE

IS USUALLY "FLAT" ENOUGH

TO JUST WRITE " v_i " AS

A SINGLE VALUE.

MOMENTUM CONSERVATION

MORE CARE AND EFFORT IS
NEEDED !!

$$\rho \left(\frac{\partial \vec{v}}{\partial t} + \vec{v} \cdot \nabla \vec{v} \right) = -\nabla p + \nabla \cdot \vec{\tau} + \rho \vec{g}$$

START THIS WITH THE SAME
VOLUME INTEGRAL

$$\int_V \rho \left(\frac{\partial \vec{v}}{\partial t} + \vec{v} \cdot \nabla \vec{v} \right) dV =$$

$$\int_V \left(\nabla p + \nabla \cdot \vec{\tau} + \rho \vec{g} \right) dV$$

SAME AS $\frac{d\vec{p}}{dt} = \sum \vec{F}$

WE SELECTIVELY CHOOSE
EITHER LEAVING A VOLUME
INTEGRAL OR CONVERTING
TO A SURFACE INTEGRAL

$$\int_V \rho \frac{\partial \vec{v}}{\partial t} dV = \frac{d}{dt} \int_V \rho \vec{v} dV$$

RATE OF CHANGE OF
ALL MOMENTUM IN V

$$\int_V \rho (\vec{v} \cdot \nabla \vec{v}) dV = \int_S \vec{v} \rho (\vec{n} \cdot \vec{v}) dS$$

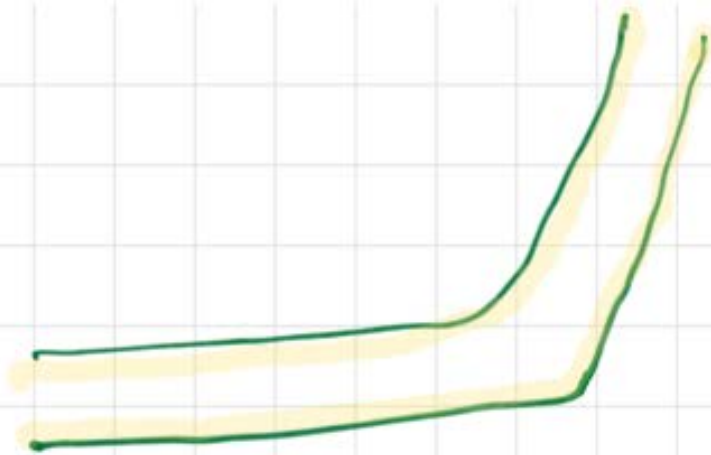
S ALLOWS
TRACKING OF
MOMENTUM IN
AND OUT

$$\int_V \nabla \cdot \vec{\tau} dV = \int_S \vec{n} \cdot \vec{\tau} ds$$

THIS INTEGRAL CONTAINS ALL OF THE VISCOUS STRESS ACTING ON THE WALLS. WE USUALLY DON'T ACTUALLY EVALUATE THIS

$$\int_V -\nabla p dV = - \int_S p \vec{n} ds$$

THIS INTEGRAL CONTAINS THE PRESSURE ACTING ON ALL WALLS AND OPEN SURFACES. WE WILL EVALUATE IT ONLY ON OPEN SURFACES!!

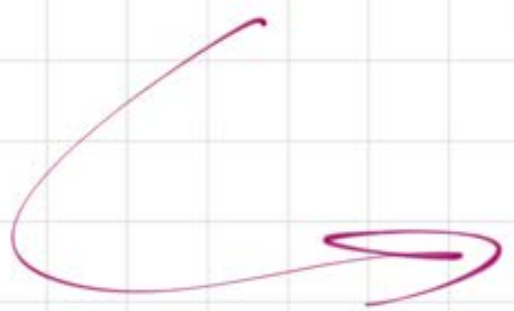


$$\int (\vec{n} \cdot \vec{c}) ds$$

SOLID SURFACES

$$- \int p \vec{n} ds$$

SOLID SURFACE



SET EQUAL
TO \vec{F}

\vec{F} IS THE TOTAL VECTOR ACTION OF THE SOLID WALLS ON THE FLUID. WE GET THIS FROM THE OTHER TERMS

$$\int_V \rho \vec{g} dV = m \vec{g}$$

THUS:

$$\frac{d}{dt} \left(\int_V \rho \vec{v} dV \right) + \int_S \vec{v} \rho (\vec{n} \cdot \vec{v}) dS =$$
$$-\int_S \rho \vec{n} dS + \int_S (\vec{n} \cdot \vec{c}) dS + m \vec{g}$$

WE NEED TO CONSIDER HOW WE CAN BEST USE THESE EQUATIONS.

NEED: SOME BODY OF EXPERIENCE

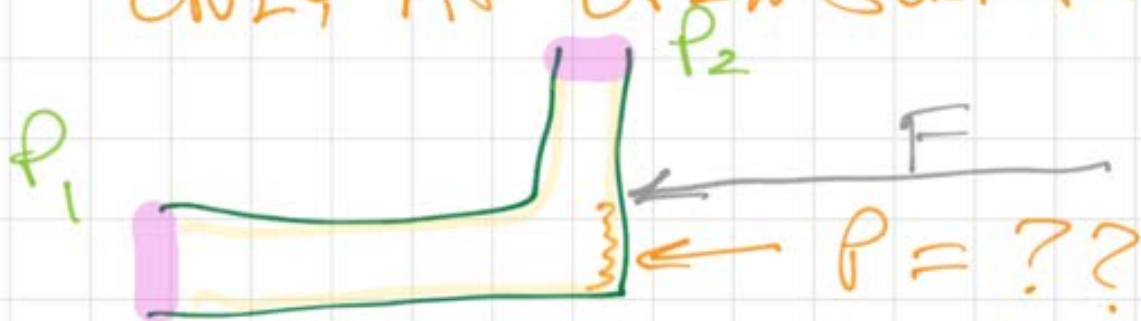
NEED: SIMPLER FORMS

COMMENTS ABOUT FORCE TERMS

PRESSURE

$$-\int_A p \vec{n} ds$$

USUALLY WE KNOW PRESSURE ONLY AT OPEN SURFACES



SO I DON'T EVEN TRY !!

$$\int_S \vec{n} \cdot \vec{c} ds = \text{TOTAL FORCE ALONG WALLS}$$
$$= F$$

FORCE NEEDED TO HOLD FITTING IN PLACE

$$\int \rho \vec{g} dV = m \vec{g}$$

GRAVITY FORCE
ON ENTIRE
CONTROL VOLUME

WE WILL CONSIDER SOME
EXAMPLE SITUATIONS

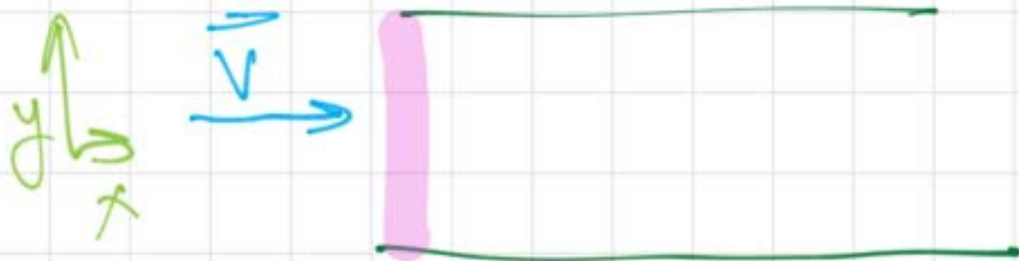


$$\int_A \vec{v} \rho (\vec{v} \cdot \vec{n}) ds$$

MOMENTUM
VOLUME

ACTUAL INFLOW OR
OUTFLOW VELOCITY
(SCALAR)

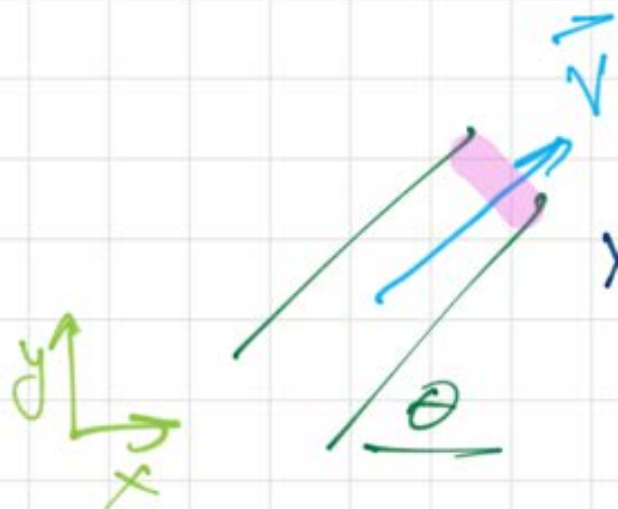
$$= \rho \langle v_x v_x \rangle_1 A_1 - \rho \langle v_x v_x \rangle_2 A_2$$



$$\int \vec{v} \cdot (\vec{v} \cdot \vec{n}) dS = - \int \rho \vec{v} \cdot \vec{v}_x dS$$

V IS A 2D QUANTITY: v_x

$$- \int \rho v_x v_x dS = - \rho \langle v_x v_x \rangle A$$



$$x \Rightarrow \int \rho |\vec{v}| \cos \theta (\vec{v} \cdot \vec{n}) dS = \rho v_x Q$$

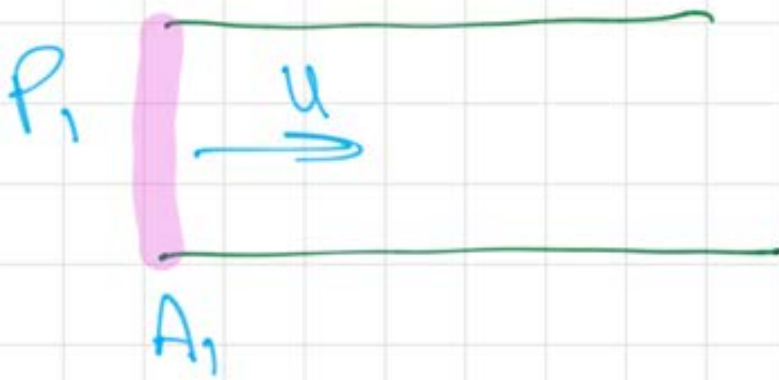
$$y \Rightarrow \int \rho |\vec{v}| \sin \theta (\vec{v} \cdot \vec{n}) dS = \rho v_y Q$$



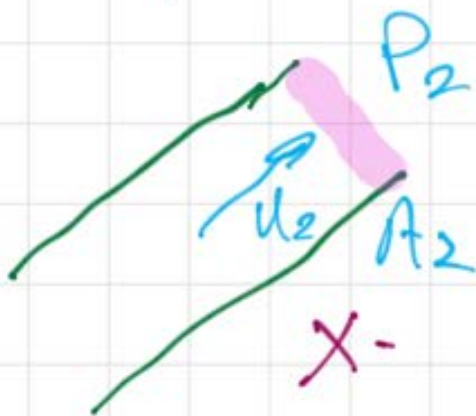
$$\rho V_1 A_1 = \rho V_2 A_2$$

$$\begin{aligned}
 x \quad 0 &= -\rho \langle V_x V_x \rangle_1 A_1 + \rho V_x Q \Big|_2 \\
 &= -\rho V_1^2 A_1 + \rho V_2 \cos \theta V_2 A_2
 \end{aligned}$$

$$\begin{aligned}
 y \quad 0 &= 0 + \rho V_y Q \Big|_2 \\
 &= 0 + \rho V_2 \sin \theta V_2 A_2
 \end{aligned}$$

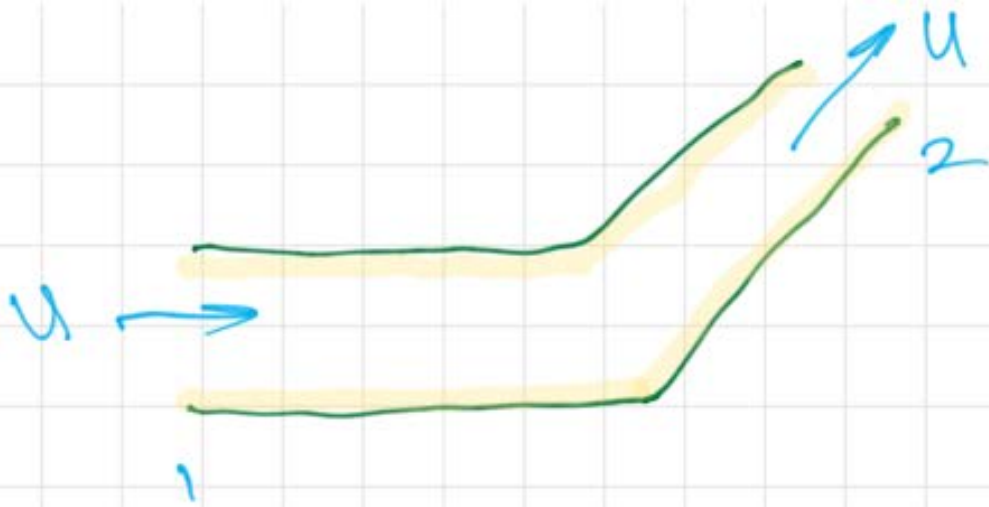


$$x - \int_{A_1} P \vec{n} ds = P_1 A_1$$



$$x - \int_A P \vec{n} ds = -P_2 \cos \theta A_2$$

$$y - \int_A P \vec{n} ds = -P_2 \sin \theta A_2$$



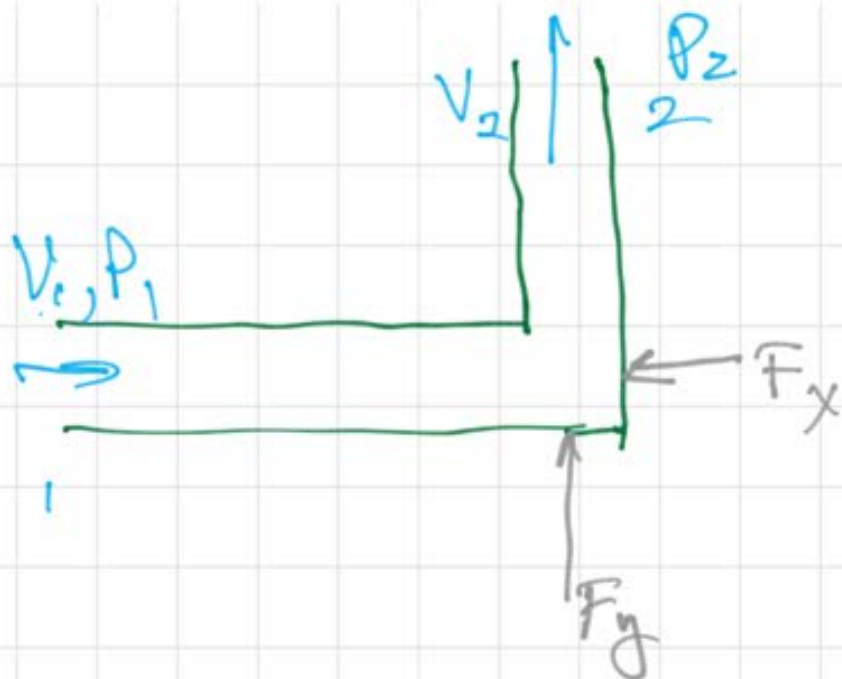
$$\int (\vec{n} \cdot \vec{c}) ds = F_x \hat{i} + F_y \hat{j}$$

COMBINATION OF PRESSURE
AND SHEAR STRESS
USUALLY CAN'T EVALUATE
INTEGRALS EXACTLY

SO: COMPLETE BALANCE

$$x - \rho V_1^2 A_1 + \rho V_2^2 \cos \theta A_2 = P_1 A_1 - P_2 A_2 \cos \theta + F_x$$

$$y - 0 + \rho V_2^2 \sin \theta A_2 = -P_2 A_2 \sin \theta + F_y$$



$$\sum F_x - \rho V_1^2 A_1 = P_1 A_1 + F_x$$

$$F_x = -P_1 A_1 - \rho V_1^2 A_1$$

FORCE MATCHES PRESSURE
AND DEFLECTS COMPLETE
FLOW

$$\sum F_y + \rho V_2^2 A_2 = -P_2 A_2 + F_y$$

$$F_y = P_2 A_2 + \rho V_2^2 A_2$$